The Method of Lagrange Multiplier

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 In mathematical optimization, the method of Lagrange multipliers is a strategy for finding the local maxima and minima of a function subject to equation constraints

max
$$f(x)$$

s.t. $g_i(x) = 0, i = 1, 2, \cdots, m$

• It is named after the mathematician Joseph-Louis Lagrange

- The basic idea is to convert a constrained problem into a form such that the derivative test of an unconstrained problem can still be applied
- In general, the Lagrangian (or Lagrangian function) is defined by

$$\mathcal{L}(x,\lambda) = f(x) + \sum_{i=1}^{m} \lambda_i g_i(x)$$

where λ_i is called the Lagrange multiplier

• In order to find the maximum (or minimum) of function f subject to the equality constraints $g_i(x) = 0$, find the stationary points of \mathcal{L} considered as a function of x and the Lagrange multiplier λ

$$rac{\partial \mathcal{L}}{\partial x} = 0$$
 and $rac{\partial L}{\partial \lambda} = 0$

• Equivalently,

$$\frac{\partial f(x)}{\partial x} + \sum_{i=1}^{m} \lambda_i \frac{\partial g_i(x)}{\partial x} = 0 \text{ and } g_i(x) = 0, \forall i = 1, 2, \cdots, m$$

• A rectangular box without a lid is to be made from $27m^2$ of cardboard. Find the maximum volume of such a box

Theorem (Lagrange Multiplier Theorem)

Let $f : \mathbb{R}^n \to \mathbb{R}$ be the objective function, $g : \mathbb{R}^n \to \mathbb{R}^m$ be the constraint function, both of which have continuous fist derivatives. Let x^* be an optimal solution to the following optimization problem

$$\begin{array}{ll} \max & f(x) \\ \mathrm{s.t.} & g(x) = 0 \end{array}$$

such that $\operatorname{Rank}(\operatorname{Dg}(x^*)) = m < n$ for the matrix of partial derivatives $[\operatorname{Dg}(x^*)]_{j,k} = \frac{\partial g_j}{\partial x_k}$. Then, there exist a unique Lagrange multiplier $\lambda^* \in \mathbb{R}^m$ such that

$$\mathsf{D}f(x^*) = (\lambda^*)^T \mathsf{D}g(x^*)$$

- At any local maximum (or minimum) of the function evaluated under the equality constraints, if constraint qualification applies, then the gradient of the function (at that point) can be expressed as a linear combination of the gradients of the constraints (at that point), with the Lagrange multiplier serving as coefficients
- This is equivalent to saying that, any direction perpendicular to all gradients of the constraints is also perpendicular to the gradient of the function
- More details can be found at https://en.wikipedia.org/wiki/ Lagrange_multiplier

Thanks!

Q & A